ChartPoint: Guiding MLLMs with Grounding Reflection for Chart Reasoning

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Abstract

001 Multimodal Large Language Models (MLLMs) have emerged as powerful tools for chart comprehension. How-002 003 ever, they heavily rely on extracted content via OCR, which leads to numerical hallucinations when chart textual an-004 notations are sparse. While existing methods focus on 005 scaling instructions, they fail to address the fundamental 006 challenge, i.e., reasoning with visual perception. In this 007 008 paper, we identify a critical observation: MLLMs exhibit 009 weak grounding in chart elements and proportional relationships, as evidenced by their inability to localize key po-010 sitions to match their reasoning. To bridge this gap, we 011 012 propose PointCoT, which integrates reflective interaction 013 into chain-of-thought reasoning in charts. By prompting 014 MLLMs to generate bounding boxes and re-render charts based on location annotations, we establish connections be-015 tween textual reasoning steps and visual grounding regions. 016 We further introduce an automated pipeline to construct 017 018 ChartPoint-SFT-62k, a dataset featuring 19.2K highquality chart samples with step-by-step CoT, bounding box, 019 and re-rendered visualizations. Leveraging this data, we 020 develop two instruction-tuned models, $ChartPoint_{O2}$ and 021 ChartPoint_{02.5}, which outperform state-of-the-art across 022 several chart benchmarks, e.g., +5.04% on ChartBench. 023

024 1. Introduction

Recently, with Large Language Models (LLMs) demon-025 strating strong understanding and generalization capabil-026 ities [4, 8, 50, 55], Multimodal Large Language Models 027 028 (MLLMs) have become the mainstream for processing multimedia data such as images and videos [5, 36, 41, 49]. 029 Charts, as an intuitive way to present complex data, are 030 widely adopted in documents and on the internet. However, 031 032 current MLLMs heavily rely on optical character recognition (OCR) results when processing charts. When the text 033 information extracted by OCR is limited, the MLLMs strug-034 gle to interpret the charts accurately, even leading to numer-035 ical hallucinations [35, 59, 65]. Thus, extracting chart con-036 tent accurately and attaining profound chart comprehension 037 038 continues to be challenging tasks.

Question: According to this chart, for Japan, what is the Sales in thousands at Years 2021?



Figure 1. Comparison between vanilla CoT and proposed CoT with bounding box reflection on Qwen2-VL [58]. Vanilla CoT fails to introduce visual-level reflections. We re-render the generated BBox on the query chart to verify area focus and successfully improve the precision of the extracted numbers.

Existing methods attempt to address this issue through 039 Supervised Fine-Tuning (SFT), including using more 040 instruction-tuning data [21, 35, 43], increasing the chart res-041 olution [75], or adopting more meticulously crafted align-042 ment training techniques [44, 66, 68]. However, MLLMs 043 still exhibit a limited perception of chart content. Recently, 044 the inference-time scaling law and the reasoning models 045 trained on it have exhibited impressive and in-depth reason-046 ing capabilities [20, 82]. Chain-of-Thought (CoT) training 047 has notably enhanced LLMs' proficiency in mathematics, 048 logic, and code [60, 79]. This motivates us to refine reason-049 ing paradigms and inference formats of MLLMs on charts, 050 especially in scenarios with sparse text annotations. 051

Do current MLLMs truly grasp the correct logic for chart 052 interpretation? As depicted in Fig. 1, while the MLLMs 053 present reasonable steps for chart-reading, the numbers 054 they extract still contain significant errors. This situation 055 prompts a crucial question: do MLLMs rely excessively 056 on the extracted numbers when interpreting charts, thus 057 lacking the capacity to read from chart elements and pro-058 portional relationships? To explore this, we employ the 059 MLLMs [6, 58] with satisfying localization capabilities, 060 which can denote object positions using bounding boxes 061 (BBox) or points. We prompt the model to point out 062

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the positions that match each reasoning step. Regrettably, 063 064 MLLMs either overlook this request or generate entirely irrelevant positions. This implies that while the CoT ap-065 proach bolsters the MLLM's logical processing based on 066 067 numbers, it fails to enhance the model's fundamental numerical perception. Although CoT generates more infer-068 ence tokens, it fails to enable additional interactions with 069 chart or visual tokens, leading to limited perceptual im-070 071 provement of MLLMs [27, 51]. Hence, we enhance CoT by incorporating a reflective interaction process, where the 072 073 model outputs BBoxes and engages with re-rendered charts (Fig. 1). Hence, we construct CoT data with BBox re-074 flection called PointCoT. We enhance the model's reason-075 ing chain through a structured inference process and in-076 077 troduce an automated annotation pipeline leveraging chart-078 code pairs and advanced LLMs for precise step decomposition and key position localization. 079

080 This pipeline consists of four stages. 1) Step Decomposition: We collect high-quality chart-code pairs and use 081 LLMs to generate a numerical question and corresponding 082 CoT reasoning steps. The LLM labels each step as Ground-083 084 ing (requiring chart data extraction) or Reasoning. We will 085 add point markers on the chart for all grounding steps. 2) Code Editing: LLMs modify the code for all grounding 086 steps by inserting special characters at key positions for 087 easier position extraction. Directly employing MLLMs is 088 unreliable for this task. Hence, we employ LLM-based 089 090 code editing to achieve high success. Thus, each grounding step has a corresponding edited code. 3) Code Ren-091 dering: We execute all modified code and re-render the 092 charts. If any CoT step fails or triggers warnings, we dis-093 card the sample. 4) Position Localization: We perform OCR 094 095 on each rendered chart to extract embedded character positions. Through format checks, we ultimately derive BBoxes 096 097 for grounding steps. Ultimately, we construct 19.2K samples, each containing a detailed CoT process and position 098 annotations. We further present ChartPoint-SFT-62k, 099 a dataset of 62.3K instructions, along with two SFT models 100 101 called ChartPoint_{O2} and ChartPoint_{O2.5}. We achieve significant improvements across chart benchmarks, demonstrating 102 the effectiveness of PointCoT. Our contributions are sum-103 marized as follows: 104

- a) We introduce PointCoT, which enables the MLLM to verify whether its reasoning steps align with the chart content using generated bounding boxes.
- b) We present ChartPoint-SFT-62k, a dataset containing 63.2K instruction-tuning samples. We also provide a data annotation pipeline to label the corresponding chart locations for CoT steps.
- c) We propose the ChartPoint_{Q2} and ChartPoint_{Q2.5} based on proposed instruction data. Extensive experiments demonstrate that our models achieve state-of-the-art performance in chart understanding benchmarks.

2. Related Works

Multimodal Large Language Models adopt projectors to 117 connect LLMs with visual encoders to understand im-118 ages and demonstrate remarkable performance [83]. Some 119 works employ QFormers [28] for modal alignment on large 120 image-text pair datasets [2, 5, 28, 73]. Other works fur-121 ther simplify the architecture with a linear projector and ex-122 tend the instruction tuning paradigm to visual tasks [36, 67]. 123 Training strategies and data quality are crucial for the de-124 velopment of MLLMs. The GPT series [9, 48, 50, 82] 125 and Claude series [3] are the models with SOTA perfor-126 mance. The LLaMA series [19, 54-56] initially leads the 127 open-source community and spawns works like the LLaVA 128 series [36-38]. The Qwen series [4-6, 58, 69, 70] and In-129 tern series [10, 13–15, 17, 52, 77] have further elevated the 130 performance of open-source models to SOTA level. The 131 DeepSeek series [8, 16, 20, 31, 32, 41, 61] and Mistral se-132 ries [24] conduct in-depth explorations of the Mixture of 133 Experts architecture for MLLMs. 134

Chart Reasoning involves using MLLMs for tasks like 135 question answering, description, analysis, and summariza-136 tion of charts. Two-stage methods center on generating in-137 termediate chart representations via specialized extraction 138 modules. These representations can take forms such as 139 markdown, as explored in [25, 33, 34], or dictionaries, as 140 seen in [12, 62]. Subsequently, they are supplied as text 141 prompts to LLMs. End-to-end methods attempt to opti-142 mize MLLMs with more chart-related instructions [21, 64]. 143 Alignment training is employed to supplement prior knowl-144 edge in the chart domain, e.g., tabular [11, 35, 44], mark-145 down [72, 74], JSON [68] or dictionaries [23]. Chart-146 Thinker [39] and DOMINO [57] propose the CoT for chart 147 reasoning, and LaMenDa [84] further integrates step-by-148 step reasoning into the supervised fine-tuning stage. Tiny-149 Chart [75] upsamples the chart resolution and achieves 150 a notable performance improvement. Moreover, recent 151 works [66, 71] attempt to combine the advantages of the 152 above approaches using the mixture of experts architecture. 153

Multimodal Chain of Thought aims to extend text-based 154 CoT reasoning [20, 60] to multimodal scenarios to en-155 hance performance in tasks requiring logical reasoning. 156 Some two-stage works either convert visual information 157 into text [46, 47, 79] or sample key image information (e.g., 158 region [51] or coordinate [26]). GoT [76] generates directed 159 acyclic graphs to assist reasoning. Recently, structured rea-160 soning is proposed to enhance the robustness of the CoT. 161 Both InsightV [18] and LLaVA-CoT [63] propose a reason-162 ing framework based on human design to solve a wide range 163 of visual question-answering problems. Further research 164 aims to enhance the interaction between the reasoning steps 165 and the query image in structured scenarios [27, 53]. 166



Figure 2. Chain of thought step generation based on plot code.

167 3. Proposed Method

168 3.1. PointCoT

169 To enhance the reasoning process, we focus on constructing 170 extensive thinking-chain data for chart-based Q&A while leveraging coordinate points to guide the model's attention 171 to relevant chart regions. To ensure the model learns cor-172 rect chart-reading logic, we select charts without datapoint 173 annotations, preventing it from extracting answers directly 174 via OCR. Specifically, our metadata construction is based 175 176 on the ChartAlign dataset [66], which comprises one million quadruples (table, JSON, code, chart) sourced from 177 ChartQA [42], PlotQA [45], and ChartY [12]. Our objec-178 tive is to generate chain-of-thought reasoning data for charts 179 and incorporate coordinate-based cues at each step to justify 180 the model's focus region. The following sections detail the 181 step-by-step process of constructing the training data. 182

183 3.2. Construction of Structured Reasoning

184 Researchers typically employ advanced LLMs to decom-185 pose and expand the reasoning process of the text data, 186 aiming to obtain long chain-of-thought inference processes. Recent studies have also demonstrated that distillation 187 learning based on such data enables smaller models to ac-188 quire strong reasoning abilities [20]. Unlike general vi-189 sual Q&A tasks that require diverse knowledge and rea-190 191 soning styles, chart Q&A exhibits a structured thought process, i.e., the model infers correct numbers from visual ele-192 ments like legends and coordinate systems through consis-193 tent steps, which can be enhanced with structured reasoning 194 195 training. Fig. 2 elaborately outlines the process of our reasoning data construction. Our primary focus lies in straight-196 forward chart comprehension, centered around chart data 197 points Q&A. Although the reasoning process appears struc-198 tured, this structure does not arise from artificial constraints. 199 Instead, it emerges naturally from the inherent logic of chart 200 201 reading, imparting a degree of structural consistency to the



Figure 3. The pipeline of code editing with grounding steps.

decomposed CoT steps.

Fig. 2 presents an example chart and the generated 203 JSON. First, we utilize the teacher model (i.e., Qwen2.5-204 72B [70]) to pose a datapoint-related question based on the 205 plotting code. We require the teacher to provide a step-by-206 step reasoning process and the final answer. We employ 207 few-shot examples to standardize the step-decomposition 208 format and ask the teacher model to classify each sub-step 209 into two categories: Grounding and Reasoning. Refer to 210 Appendix B for the detailed prompt. Grounding steps focus 211 on identifying the positions of chart elements, such as locat-212 ing points on the axes or entries in the legend. Reasoning 213 steps involve making logical inferences based on informa-214 tion obtained from previous grounding steps. This classifi-215 cation helps incorporate specific bounding boxes for steps 216 that require element localization, thereby offering precise 217 positional guidance. Finally, we instruct the teacher model 218 to generate outputs in JSON format. Samples that pass both 219 the format validation and key integrity checks proceed to 220 the following processing stage. 221

3.3. Construction of Point Annotation

Our goal is to incorporate location supervision into all 223 grounding steps, guiding the model to follow human-like 224 chart-reading logic. We believe the generated bounding 225 boxes not only validate the grounding steps but also en-226 courage the model to re-examine the original input chart. 227 Therefore, we implement point-based CoT training through 228 grounding. MVoT [27] also achieves similar observations 229 in other structured scenarios, e.g., puzzle-solving games. 230

Fig. 3 elaborately depicts how we add the position points231to all grounding steps. Our modifications are based on revising the plotting code and OCR on the re-rendered chart.232Specifically, we instruct the teacher model to identify the relevant elements (e.g., legend or title) or positions (e.g., datapoints or corresponding horizontal and vertical coordinates) for each grounding step. Next, the teacher model231

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Figure 4. The process pipeline for constructing instruction data. The red / green indicates the instruction prompt / ground truth. Table 1. Data processing steps and corresponding success rate. # indicates the number of instructions.

Processing Step	Meta	CoT	Code	Render	OCR	QA#
Chart Number	66.84K	64.28K	48.75K	24.88K	19.2K	62.3K
Success Rate	-	96.17%	75.84%	51.04%	77.17%	-

modifies the plotting code based on the identified positions
by inserting a special symbol into the chart element text or
marking a specific position using plt.text(). This insertion not only highlights key positions but also facilitates
the quick detection of unique characters with OCR tools.

After passing the integrity check, the edited code is re-243 rendered to generate the updated chart. We then apply OCR 244 to the re-rendered chart to extract the coordinates of the in-245 serted special characters. To enhance extraction accuracy 246 247 and success rates, we employ multiple OCR tools sequentially. A minimum width is defined for the bounding boxes 248 generated by special characters, and any boxes more minor 249 than the threshold are adjusted based on the center point and 250 the pre-set width. Each grounding step is associated with an 251 edited code, a re-rendered chart, and the detected positions 252 253 from OCR. Refer to Appendix A for details.

254 3.4. Construction of Instruction

After obtaining the bounding boxes for all grounding
steps, we begin constructing instruction data with location annotations. Fig 4 illustrates the process to construct
ChartPoint-SFT-62k, which primarily includes four
formats and 62K Q&A pairs.

Type 1: Standard VOA. The raw chart and question are 260 used as input. 1) Supervised with ground truth answer. Un-261 262 like previous ChartOA [42], the data points are not directly labeled with text, making the questions more challenging. 263 2) Supervised with CoT steps and the answer as long text 264 supervision. Here, the bounding boxes from the ground-265 ing step are excluded to prevent potential data leakage and 266 avoid affecting other formats. Type 2: Localization Task. 267 268 Different from direct Q&A, we introduce intermediate steps



Figure 5. Statistic information of ChartPoint-SFT-62k. Left: Statistics on the number of CoT steps w.r.t. grounding, reasoning, and total steps. Right: chart type distribution.

Table 2. Instruction data used for ChartPoint superivised training.

Dataset	Description	Number						
Chart Kn	owledge Alignment Stage							
MMC-Instruct [35]	VQA / Summariztion/ Reasoning	410K						
ChartGemma [43]	VQA / Summariztion/ Reasoning	160K						
ChartQA [42]	VQA	28K						
ChartBench [65]	VQA	30K						
Chart Specific Annealing Tuning Stage								
ChartPoint-SFT-62k	VQA / Reasoning	62K						

into the query prompt. The ground truth is changed from the answer to the predicted bounding box, which is a localization task. *Type 3: Reasoning with Edited Chart.* The bounding box annotations in the previous grounding steps will be redrawn on the vanilla chart to attract attention to the key position, aiding the model in learning the correct visual reasoning logic. If the next step is also a grounding step, the model will continue to predict the next bounding box based on the edited chart. *Type 4: Reasoning Steps.* If the next step is the reasoning step, it will be added to the query prompt directly. Once the final step is processed, the supervised ground truth will be the final answer.

3.5. Quality Control

Considering the lengthy data generation process, we imple-282 ment quality control at every step and track success rates. 283 As shown in Tab. 1, we randomly sample 66.84k quadru-284 ples from ChartMoE-Align [66]. 1) We expand the rea-285 soning process based on the plot code and perform the in-286 tegrity check on the generated JSON (Fig. 2). We employ 287 GPT-40 [49] to review the generated Q&A given the metat-288 able data to filter out mismatched samples. The pass rate is 289 96.17%. 2) We modify the plotting code by incorporating 290 the grounding step as the instruction (Fig. 3). We ensure the 291 code integrity and verify the presence of the required unique 292 character in the code. The pass rate is 75.84%. 3) We exe-293 cute the modified code to render the edited charts. One case 294 will be discarded if any code execution fails, resulting in a 295 lower success rate of 51.04%. 4) We use OCR to detect spe-296 cial characters and extract the bounding boxes. We discard 297 the cases where OCR fails or detects multiple occurrences. 298

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Models	Para. Baseline	Baseline	Pes	Rela	x Acc @(0.05	Relax Acc @0.10			Relax Acc @0.20		
wodels		1.05.	Human	Aug.	Avg.	Human	Aug.	Avg.	Human	Aug.	Avg.	
General MLLMs												
LLaVA-v1.5 [38]	13B	Vicuna [80]	@336	25.36	18.56	21.96	28.56	23.52	26.04	32.56	30.72	31.64
Qwen-VL [5]	9.6B	Qwen [4]	@448	40.48	79.76	60.12	43.20	82.56	62.88	47.52	85.76	66.64
Phi-3.5-Vision [1]	4.2B	Phi-3.5[1]	Ada.	60.08	83.52	71.80	64.00	85.92	74.96	68.16	89.36	78.76
InternlmXC-v2 [17]	8B	InternLM-v2 [10]	@490	62.72	81.28	72.00	66.72	84.08	75.40	70.80	86.56	78.68
InternVL-v2.5 [14]	8B	InternLM-v2.5 [10]	Ada.	65.44	86.48	75.96	67.36	86.88	77.12	68.80	87.44	78.12
DeepSeekVL2 [61]	27B	DeepSeek-v2 [31]	@384	65.52	87.76	76.64	67.52	88.08	77.80	69.60	88.96	79.28
Qwen2-VL [58]	7B	Qwen2 [69]	Ada.	72.08	94.24	83.16	75.76	94.72	85.24	78.24	95.76	87.00
Qwen2.5-VL [6]	7B	Qwen2.5 [70]	Ada.	78.96	93.76	86.36	81.12	94.16	87.64	83.60	94.72	89.16
			Spe	cialist Char	t Models							
Matcha [34]	282M	Pix2Struct [25]	Ada.	37.12	86.64	61.88	39.84	87.36	63.60	43.52	88.56	66.04
ChartVLM [62]	13B	Vicuna [80]	Ada.	42.08	82.48	62.28	43.84	82.88	63.36	46.00	83.28	64.64
DocOwl-v1.5 [22]	8B	mPLUG-Owl2 [74]	@448	47.44	91.52	69.48	51.92	92.08	72.00	56.72	93.12	74.92
Deplot [33]	13.2B	LLaVA-v1.6 [37]	Ada.	53.44	87.68	70.56	56.80	88.48	72.64	60.64	90.08	75.36
OneChart [12]	13.3B	LLaVA-v1.6 [37]	@1024	54.48	87.12	70.80	57.60	87.84	72.72	62.00	88.64	75.32
ChartLlama [21]	13B	LLaVA-v1.5 [38]	@336	58.40	93.12	75.76	61.20	93.60	77.40	63.52	94.00	78.76
ChartGemma+PoT [43]	3B	PaliGemma [7]	@448	67.84	85.28	76.56	68.64	85.84	77.24	69.84	86.32	78.08
ChartAst [44]	13B	Sphinx [30]	@448	64.88	93.12	79.00	66.24	93.84	80.04	67.44	94.32	80.88
TinyChart+PoT [75]	3B	TinyLlava [78]	@768	70.24	90.72	80.48	71.20	91.44	81.32	72.40	92.56	82.48
ChartMoE+PoT [66]	8B	InternlmXC-v2 [17]	@490	78.32	90.96	84.64	80.16	92.32	86.24	82.08	93.60	87.84
ChartPoint _{O2}	7B	Qwen2-VL [58]	Ada.	76.12	94.48	85.28	78.36	94.96	86.66	81.28	95.12	88.20
ChartPointo2 5	7B	Owen2.5-VL [6]	Ada.	81.36	94.12	87.74	82.40	95.24	88.82	84.48	95.76	90.12

Table 3. The relaxed accuracy (%) performance on *ChartQA*. Ada:: Adaptive input resolution. Methods are sorted by relaxed average accuracy@0.05. All results are reproduced in the same inference manner by officially released model weights and prompts.

This step achieves a success rate of 77.17%. Finally, we construct 19.2K charts and 62.3K instruction data as illustrated in Fig. 4. We randomly sample 100 cases, which are reviewed by at least three experts to evaluate the bounding box quality of the grounding step based on the process in Fig. 2. 91% of the cases meet the desired standard.

305 3.6. Statistics

Fig. 5 presents the statistics of ChartPoint-SFT-62k. 306 As shown in Fig. 5 (left), we carefully count all the CoT 307 308 steps and organize the samples based on the length of the 309 CoT steps. Most samples contain 3-5 CoT steps. Notably, the grounding steps are typically longer (length > 310 3) than the reasoning steps, which are predominantly short 311 (length < 3) and generally focus on summary-style analy-312 ses. This is because our Q&A primarily addresses numer-313 ical data points without requiring complex numerical rea-314 soning, allowing the dataset to effectively capture the es-315 316 sential visual logical based more on grounding. As shown in Fig. 5 (right), we primarily focus on three chart types, 317 i.e., line (33.6%), pie (9.3%), and bar (57.1%) charts, 318 which is consistent with the distribution of mainstream 319 chart datasets [42, 45]. 320

321 3.7. ChartPoint

We integrate bounding box reflection into the inference. The baseline's grounding ability is critical for instruction tuning. Hence, we select Qwen2-VL [58] and Qwen2.5-VL [6] as baselines due to their comprehensive grounding capabilities. They can be deployed based on LLaMA-Factory [81] to conduct convenient training. We perform a two-stage full fine-tuning process using the data in Tab. 2. We utilize high-quality instruction data (includ-
ing real-world annotated and diversely synthesized charts)329for chart knowledge alignment to enhance the baseline's
performance. Then, we refresh the learning rate and
conduct chart-specific annealing tuning in our PointCoT
manner. The SFT models are named ChartPoint $_{Q2}$ and
ChartPoint $_{Q2.5}$, respectively.329Table 2. We utilize high-quality instruction data (includ-
ing real-world annotated and diversely synthesized charts)330Table 3. Second 2. Second 3. Second 3.

4. Experiment

4.1. Implement Details

ChartPoint is initialized from Qwen [6, 58], which employs 338 a dynamic resolution input strategy. We keep all numerical 339 coordinates within the range of 0 - 999 to adapt to the tok-340 enizer and the pretrain format of the coordinate system. We 341 use LLaMA-Factory [81] for supervised fine-tuning over 2 342 epochs. In the first 1% of the training steps, we implement 343 a warmup phase with a learning rate of 5e - 5. We adopt 344 the AdamW [40] optimizer with a constant weight decay of 345 0.1 throughout the training. The gradient clip is set to 1.0. 346 We conduct gradient accumulation with an equivalent batch 347 size of 64 and train using *bfloat16* precision. The training 348 process consumes around 262 GPU Hours (A100-40G). 349

4.2. Benchmarks

ChartQA [42] test split comprises 1,250 questions from351both human-generated and augmented segments. The charts352are sourced from web crawls with three prevalent chart353types. ChartQA requires the model to respond to questions354with only a single word or phrase and employs a lenient355matching method to verify the correctness of the answers.356Considering the impact of inference length on performance,357

Regular Type Extra Type Models ALL Line Bar Area Box Radar Scatter Node Combin. Pie Avg. Avg. General MLLMs LLaVA-v1.5 [38] 29.12 21.26 17.28 22.10 21.73 20.94 27.50 23.47 36.80 24.30 24.96 23.38 Qwen-VL [5] 38.00 20.71 38.24 29.46 28.83 24.17 35.00 19.50 18.50 25.50 26.56 28.18 Mini-Gemini [29] 34.88 40.40 36.77 31.20 23.33 30.60 35.20 43.60 27.9030.61 34.37 36.12 InternlmXC-v2 [17] 68.16 48.74 56.60 54.50 27.47 25.33 40.10 52.93 50.40 46.20 39.72 48.41 InternVL-v2.5 [14] 75.20 48.31 52.00 55.09 32.00 20.00 44.00 45.33 70.00 48.00 42.11 49.43 DeepSeekVL2 [61] 69.28 49.66 47.40 53.71 40.80 44.40 40.50 45.40 59.50 51.31 53.02 76.14 Qwen2-VL [58] 74.40 50.77 63.00 58.36 56.93 40.00 50.00 81.33 64.00 68.00 59.40 58.90 Qwen2.5-VL [6] 80.88 54.06 68.20 62.73 37.33 46.13 51.90 72.27 74.40 74.00 57.26 60.91 Specialist Chart Models 5.05 5.40 Matcha [34] 6.80 3.60 5.18 0.27 1.60 6.20 3.46 4.80 5.81 4.84 ChartVLM [62] 21.92 14.16 10.50 7.47 8.00 7.87 5.40 10.50 8.38 11.96 15.16 7.87 ChartLlama [21] 26.8018.83 20.80 20.99 14.27 12.00 24.30 27.73 26.20 25.80 21.71 21.31 TinyChart [75] 32.40 25.81 22.50 26.71 10.13 14.80 13.40 28.14 10.80 21.60 22.56 22.51 31.20 26.46 24.00 21.34 13.34 24.00 41.34 42.00 31.57 27.62 27.09 31.00 Deplot [33] OneChart [12] 41.28 30.28 29.60 32.65 19.07 13.20 24.60 38.53 34.80 27.9031.91 29.93 DocOwl-v1.5 [22] 49.60 31.69 31.54 35.68 12.27 23.33 22.50 36.13 29.60 38.80 27.38 32.05 50.48 38.21 32.10 39.89 28.27 24.13 28.10 48.00 41.80 43.40 42.47 38.46 ChartGemma [43] 49.20 ChartMoE [66] 71.44 51.57 52.80 56.31 38.40 24.13 40.20 62.67 58.00 55.58 51.67 ChartPoint_{Q2} 79.84 54.58 68.24 63.04 58.20 44.12 52.40 83.67 68.24 68.92 62.09 62.61 ChartPointo2.5 82.40 58.88 71.40 51.44 48.33 56.90 78.00 80.20 65.03 65.95 66.71 77.27

Table 4. The accuracy (%) performance on *ChartBench*. Our proposed ChartPoint consistently outperforms other MLLMs remarkably.

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instead of prompting the model to produce the shortest pos-358 sible answers, we adopt a template-based answer extraction 360 method, i.e., provide your final answer in box. Refer to Appendix B for details. This approach effectively enhances 361 the performance of mainstream models. 362

ChartBench [65] offers charts that lack data point annota-363 364 tions. It encompasses 9 main categories and 42 subcategories, with each sub-category housing 50 charts. Chart-365 366 Bench emphasizes the reliability of chart numbers, presenting a stiffer challenge since models are unable to obtain pre-367 cise answers via OCR. The models must understand each 368 element of the chart to estimate values close to the ground 369 truth. This benchmark uses a relaxed accuracy similar to 370 371 ChartQA, and we also adopt the inference prompt of tem-372 plate extraction to boost model performance.

373 4.3. Comparative Models

We divide all methods into two groups: general MLLMs 374 375 and those specifically designed for chart understanding.

General MLLMs. We compare LLaVA-v1.5 [38], which 376 paved the way for image-text interaction through visual in-377 378 struction fine-tuning. We also compare the QwenVL series, including v1 [5], v2 [58], and v2.5 [6]. Due to its 379 strong base performance, we set this series as the baseline 380 for our ChartPoint. We select Phi-3.5-Vision [1], which is 381 382 easy to deploy on the edge devices, and the Intern series 383 for their high performance, such as InternImXComposer-384 v2 [17] and InternVL-v2.5 [14]. We also provide the result 385 of DeepSeekVL2 [31], which is based on the MoE architecture. Note that we chose the versions of these models at 386 around 10B for fair comparisons. 387

Specialist chart models. We provide classic chart meth-388 389 ods like Matcha [34] and Deplot [33]. However, we

adopt LLaVA-v1.6 [37] to further analyze and summarize 390 their output for meaningful comparisons. We also com-391 pare ChartVLM [62], ChartAst [44], DocOwl-v1.5 [22], 392 OneChart [12], and ChartLLama [21], which are fine-393 tuned with chart-specific instructions. Since the Program 394 of thought (PoT) can effectively improve the numerical cal-395 culation ability of MLLMs, we select ChartGemma [43], 396 TinyChart [75], and ChartMoE [66] for comparisons. 397

4.4. Comparison with SOTA

Comparisons on ChartOA. Tab. 3 presents the performance 399 of ChartPoint on ChartQA. We report the relaxed accu-400 racy for three different margins and provide detailed re-401 sults for two distinct parts. ChartPoint significantly out-402 performs the baselines, e.g., ChartPoint_{O2} 83.16% [58] 403 vs. 85.28% (+2.12%[↑]) and ChartPoint_{Q2.5} 86.36% [6] vs. 404 87.74% (+1.38%[†]). Even though the Qwen-VL series 405 models demonstrate sufficiently high baseline performance, 406 ChartPoint still manages to achieve remarkable enhance-407 ments, especially in the challenging Human-annotated part. 408 This indicates that point-based CoT training can signif-409 icantly improve the model's ability to read and under-410 stand charts. Notably, ChartPoint also outperforms PoT-411 based methods [43, 66, 75]. For example, when compared 412 with ChartMoE+PoT [66], ChartPoint attains 84.64% vs. 413 87.74% (+3.10%[†]). This implies that increasing the rea-414 soning length contributes to enhancing the model's numer-415 ical and logical capabilities, effectively overcoming scenar-416 ios involving extensive numerical calculations. 417

Comparisons on ChartBench. Tab. 4 shows the perfor-418 mance of ChartPoint on ChartBench, where we report the 419 detailed performance across 9 types of charts. Compared **420** to ChartQA, ChartPoint demonstrates more significant im-421

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Table 5. Ablation study of training data in Tab. 2. CoT: stage 2 adopts the CoT data generated by Fig. 2. PointCoT: stage 2 adopts ChartPoint-SFT-62k.

Settings	0	hartQA		ChartBench			
bettings	Human	Aug.	Avg.	Regular	Extra	Avg.	
Qwen2-VL	72.08	94.24	83.16	58.36	59.40	58.90	
+Stage1	72.76	94.72	83.74	60.62	60.12	60.39	
+Stage1+CoT	73.58	94.64	84.11	60.94	60.54	60.76	
+Stage1+PointCoT	76.12	94.48	85.30	63.04	62.09	62.61	
Qwen2.5-VL	78.96	93.80	86.38	62.73	58.93	61.67	
+Stage1	79.16	93.88	86.52	64.22	60.82	62.68	
+Stage1+CoT	79.76	93.52	86.64	64.48	61.16	62.98	
+Stage1+PointCoT	81.36	94.12	87.74	66.71	65.03	65.95	

Table 6. Ablation study on different MLLMs. We report the average relax accuracy@0.05 on ChartQA and ChartBench. PointCoT: stage 2 adopts ChartPoint-SFT-62k.

Model	ChartQA	Δ	ChartBench	Δ
Qwen-VL [5]	65.70	-	28.18	-
+PointCoT	66.12	+0.42	27.92	-0.26
ChartMoE [66]	81.20	-	51.67	-
+PointCoT	81.36	+0.16	51.94	+0.27
Qwen2-VL [58]	83.16	-	58.90	-
+PointCoT	84.84	+1.68	62.12	+3.22
Qwen2.5-VL [6]	86.36	-	61.67	-
+PointCoT	87.48	+1.12	65.66	+3.99

provements on ChartBench, e.g., ChartPoint_{O2} 58.90% [58] 422 423 vs. 62.61% (+3.71%[†]) and ChartPoint_{02.5} 60.91% [6] vs. 65.95% (+5.04% \uparrow). While better OCR capabilities can 424 enhance model performance on ChartQA, ChartBench fo-425 cuses on data points without text annotations, which bene-426 fits more from superior chart element localization and rea-427 soning abilities. This supports the advantage of point-based 428 429 CoT over text-only CoT. Specifically, the improvement is more significant on *extra* type charts, e.g., ChartPoint_{O2.5} 430 431 57.26% [6] vs. 65.03% (+7.77%). This suggests that Point-based CoT training enables the model to develop a 432 logical chart-reading process and comprehension skills, en-433 434 hancing its generalization even to uncommon chart types.

435 5. In-depth Analysis

436 5.1. Ablation on Training Recipe

Tab. 5 presents the ablation study on our training recipe. As 437 shown in Tab. 2, we conduct the high-quality chart knowl-438 439 edge alignment before instruction tuning (+Stage1). We 440 design detailed reasoning steps based on advanced LLMs (Fig. 2) to ensure even smaller models (\sim 7B) can also 441 benefit from inference scaling laws (+CoT). Additionally, 442 443 we integrate grounding supervision into the CoT steps, enabling the model to continuously reflect on its reasoning 444 and interact with input charts to refine the reasoning chain 445 (+PointCoT). Since the baseline model is optimized for 446 ChartQA during pre-training, the Stage1 alignment training 447 yields marginal performance improvements (e.g., Qwen2-448 449 VL +0.58% \uparrow , Qwen2.5-VL +0.14% \uparrow). Direct distillation

Table 7. Ablation study of bounding box format on ChartQA. In the ground truth, we normalize the point number into 0-1 (retain 3/4 decimal) or 0-999 to indicate the grounding area.

Settings	Normalize	Decimal	Human	Δ	Aug.	Δ	ALL	Δ
Qwen2-VL	-	-	72.08	-	94.24	-	83.16	-
Type A	[0-1]	4	73.52	+1.44	93.84	-0.40	83.68	+0.52
Type B	[0-1]	3	74.68	+2.60	94.16	-0.08	84.42	+1.26
Type C	[0-999]	0	75.36	+3.28	94.32	+0.08	84.84	+1.68

Table 8. Ablation study of prompt engineering (PE) on ChartQA. Direct: PE from ChartQA. Match: inference step by step and extract final answer via designed pattern.

Model	PE	Human	Δ	Aug.	Δ	ALL	Δ
Qwen2-VL	direct match	72.08 73.84	- +1.76	94.24 94.32	- +0.08	83.16 84.08	- +0.92
ChartPoint _{Q2}	direct match	75.22 76.12	- +0.90	94.24 94.48	- +0.24	84.73 85.28	+0.55

from reasoning steps also shows limited improvement because: 1) In Fig. 2, we adopt the LLM (not MLLM), so the reasoning process does not leverage chart information; 2) both ChartQA and ChartBench focus more on data point accuracy rather than numerical calculation or reasoning. Hence, textual CoT does not improve the model's accuracy in reading basic numbers from the chart. With grounding supervision, the model performance gets significantly improved, particularly on sparse-annotated Chart-Bench (Qwen2-VL +3.71% \uparrow , Qwen2.5-VL +4.28% \uparrow).

5.2. Ablation on Backbone

To demonstrate the effect of MLLMs for SFT based on 461 PointCoT, we select two baseline models with relatively 462 poor localization but strong chart-processing abilities for 463 comparisons. As shown in Tab. 6, PointCoT is highly de-464 pendent on the underlying localization capabilities. Al-465 though both Qwen-VL [5] and ChartMoE [66] perform ex-466 cellently in handling chart data, the reflection based on 467 BBox fails to enhance their performance further. In con-468 trast, both Qwen2-VL [58] and Qwen2.5-VL [6] can ac-469 curately indicate the objects using either points or BBoxes. 470 Correspondingly, this enables PointCoT to work effectively, 471 achieving a performance improvement of more than 1%. 472

5.3. Ablation on Bounding Box Format

Our proposed ChartPoint reflects on the chart regions 474 by outputting $(X_{\text{top left}}, Y_{\text{top left}}), (X_{\text{bottom right}}, Y_{\text{bottom right}})$ as 475 bounding boxes. Our observations reveal that the numerical 476 representation format significantly impacts the tuning pro-477 cess. Table 7 presents three formats using baselines trained 478 on ChartPoint-SFT-62k for one epoch without addi-479 tional data or tricks. Type A normalizes numbers to four-480 decimal values between 0 and 1, representing relative posi-481 tions on the chart. However, it yields only a marginal per-482 formance improvement of 0.52%. Type B rounds values to 483 three decimal places. With the same data size and training 484

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Figure 6. Comparsion between Qwen2.5-VL-72B [6], GPT-4O [49] and ChartPoint_{Q2.5} (ours). All models adhere to the output format required by the prompt. However, both Qwen2.5-VL and GPT-4O ignore the BBox instruction. With the reflective output of the BBox, our ChartPoint_{Q2.5} has extracted precise numbers, and the BBoxes have provided sound explanations.

time, it achieves a 1.26% improvement, significantly out-485 486 performing type A. Further analysis suggests that Qwen's 487 tokenizer splits decimals into three-digit segments, potentially increasing token-level training difficulty for Type A. 488 489 *Type C* retains the baseline positioning format, which varies across MLLMs, using numbers between 0 and 999 to rep-490 resent relative positions. This approach proves particularly 491 492 beneficial for grounding training, leading to a 1.68% performance improvement in just one epoch. These findings 493 highlight the importance of numerical representation in op-494 timizing model performance. 495

496 5.4. Ablation on Prompt Engineering

To effectively utilize rule-based metrics for evaluation, re-497 searchers require models to respond with a direct number 498 or phrase, i.e., *direct* prompt. However, we observe that 499 for models with excellent instruction-following capabilities, 500 performance can be further improved by extending the rea-501 soning length. This conclusion is well-established in rea-502 503 soning models [20, 82]. Still, it also applies to MLLMs that are not explicitly designed for reasoning, particularly 504 when compared to prompts that generate only a single word. 505 Tab. 8 illustrates two types of PE on both the baseline and 506 our ChartPoint $_{\Omega^2}$, with modifications applied exclusively to 507 the reasoning prompt while keeping the model parameters 508 509 unchanged. For Qwen2-VL, adjusting the PE results in a

0.92% performance improvement, particularly on the more510challenging Human subset. Although ChartPoint_{Q2} already511demonstrated strong performance, the PE provides an addi-
tional 0.55% gain on ChartQA.513

5.5. Case Visualization

Fig. 6 demonstrates specific cases from ChartQA and Chart-515 Bench. We choose the powerful Qwen2.5-VL-72B [6] and 516 GPT-40 [49] for comparison with our ChartPoint_{02.5}. We 517 request the models to output BBox when generating the 518 CoT steps to support their reasoning (Appendix B). As 519 shown in Fig. 6, only our ChartPoint_{Q2.5} provide the BBoxes 520 as required by the prompt, yielding more accurate numbers 521 on charts with sparse text annotations. 522

6. Conclusion

We propose PointCoT, a multimodal CoT training method 524 for chart understanding. We adopt the generated bound-525 ing boxes to verify whether the chain-of-thought reasoning 526 steps are in line with the chart content. Specifically, we pro-527 pose an automated annotation pipeline to provide the corre-528 sponding bounding boxes in the grounding steps and thus 529 construct an instruction dataset. We provide two supervised 530 fine-tuning models based on PointCoT data and conduct ex-531 tensive experiments to demonstrate their effectiveness. 532

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